Applications of digital processors

# SPECTRAL ANALYSIS on signal processors 

Author: Grzegorz Szwoch
Gdańsk University of Technology, Department of Multimedia Systems

## Introduction

- Samples describe values of a digital signal in the time domain.
- Many digital signal processing operations must be performed in the frequency domain. We only want to process selected frequency components, not the whole signal.
- Spectral analysis - determining spectral (frequency) components of a signal.


## Example

Time plot of a clarinet sound recording.
We don't know from this plot what the signal structure is.


## Example

The result of spectral analysis of the clarinet sound.

- We can see the signal structure - a sum of harmonics.
- We can determine the sound pitch - it is related to frequency of the first spectral peak.



## Fourier transform

- The Fourier transform converts $N$ signal samples into $N$ samples of the signal spectrum.
- The result of the transform is the signal spectrum (an analogy to the light spectrum).
- The inverse Fourier transform converts spectrum samples back into signal samples.
- A signal may be transformed into the spectrum, process it and transform back into the processed signal. This is spectral processing.



## Spectrum of a real signal

- Fourier transform works for both real and complex signals.
- The spectrum is always a set of complex numbers.
- Usually, we process real (not complex) signals.
- $N$ samples of the spectrum of a real signal:
- the first value: the direct component, a sum of samples
- values 2 to $N / 2$ : samples of the signal spectrum
- value at $N / 2+1$ : a Nyquist component, should be zero
- values $N / 2+2$ to $N$ : a mirror reflection of the first half of the spectrum (a Hermitian symmetry).
- A spectrum obtained from $N$ samples has ( $N / 2+1$ ) unique values.


## Spectrum of a real sound

We only need (N/2+1) values out of $N$ spectral samples.


## Amplitude spectrum

- Spectrum $X(f)$ contains complex values.
- Usually, we are interested in the magnitude spectrum $A(f)$, the absolute value of the complex spectrum:

$$
A(f)=|X(f)|
$$

- Power spectrum is the absolute value of the spectrum, squared:

$$
P(f)=|X(f)|^{2}
$$

- Often, we use a logarithmic spectrum, expressed in decibels (dB):

$$
\begin{aligned}
& A(f)=10 \log _{10}|X(f)| \\
& P(f)=10 \log _{10}|X(f)|^{2}=20 \log _{10}|X(f)|
\end{aligned}
$$

## Magnitude spectrum

- To obtain the amplitude of spectral components, we must divide the absolute value of the spectrum by the number of samples $N$, and multiply by two, as the signal energy is divided into two mirrored halves.
- Amplitude of a spectral component at index $n$ :

$$
A[n]=\frac{2}{N}|X[n]|
$$

- The first (DC) and the Nyquist component do not have a pair, they should not be multiplied by two.
- The direct component divided by $N$ equals to the mean of the signal within the analyzed section.


## Frequencies of the signal samples

- From $N$ signal samples, we obtain $N$ spectral samples.
- The spectrum covers the frequency range $\left[0, f_{s}\right]$.
- The $n$-th spectral component is at the frequency:

$$
f[n]=n \frac{f_{S}}{N}
$$

- Spacing between spectral values is equal to the sampling frequency divided by the number of samples.
- This is a frequency resolution of spectral analysis:

$$
d f=\frac{f_{S}}{N}
$$

## Frequency resolution

- What does frequency resolution mean $\left(d f=f_{s} / N\right)$ :
- two spectral components cannot be distinguished if they are spaced by less than $d f$ (they fall into the same spectral bin),
- inaccuracy (error) of determining the frequency of a spectral component is max. $\pm d f / 2$.
- Larger number of samples $(N)$ increases the resolution.
- Resolution may be improved by zero padding the signal before the transform. We don't get more data (the values are interpolated), but we obtain better resolution.


## Frequency resolution

Example: sum of two sines $f 1=234.375$ and $f 2=281.25 \mathrm{~Hz}$


## Periodicity of the signal

- Fourier transform assumes that the signal is periodic.
- A signal section used for the transform is assumed to be the signal period (or its multiple).
- Example for a signal in which the length of the window is a multiple of the signal period ( $f=937.5 \mathrm{~Hz} ; N=512$ ):



## Periodicity of the signal

- What happens if the analysis window length is not a multiple of the signal period?
- The result is a transform of a signal that is a "looped" analysis window.
- Example for $f=1000 \mathrm{~Hz}, N=512$ :



## Spectral leakage

How does the spectrum of such a signal look like?


This is spectral leakage - the spectral energy "leaks" to the adjacent bins.

## Spectral leakage

Example: sum of sines $1000 \mathrm{~Hz} \& 1100 \mathrm{~Hz}(N=512)$.
Spectral leakage hides the shape of individual peaks.


## Analysis windows

- Spectral leakage is a result of discontinuity at the analysis window when it is looped.
- Leakage may be suppressed if the signal is multiplied by a window function before the transform.
- The window function suppresses the samples at the edges.
- The result of applying a window:
- it reduces energy leaks to the adjacent spectral bins,
- but it also widens the peaks - the leakage is confined to a narrower range.


## Analysis windows

## The windows that are most frequently used for spectral analysis:



## Effect of a window function

Window applied to the analysis in the case of large leakage

- the result is improved (the leakage diminishes).



## Effect of a window function

Effect of applying a window when there was no leakage

- widening of the peak is visible.



## Remarks about windows

- There is no "best" window. Hamming and von Hann are the most frequently used ones.
- Blackman window is useful when we need to suppress the leakage, at the cost of widening the peaks.
- We use the window function when we analyze the spectrum, e.g. we search for the maxima.
- We do not use the window if we process the signal in frequency domain and then we get back to time domain.
- Amplitude normalization when window w is used:

$$
A[n]=\frac{2}{\sum w_{i}}|X[n]|
$$

## Computing a Fourier transform

There are two ways to compute a Fourier transform

1. From the definition of discrete Fourier transform (DFT):

- works for all signals,
- requires many multiplication and addition operations.

2. With Cooley-Tukey algorithm, also called fast Fourier transform (FFT):

- reduced number of operations,
- limitations related to the window length,
- used e.g. in digital signal processors.

FFT

Fourier transform of two samples:


$$
\begin{aligned}
& y(0)=x(0)+x(1) \cdot W_{n}^{k} \\
& y(1)=x(0)-x(1) \cdot W_{n}^{k}
\end{aligned}
$$

- We need to perform: one multiplication, one addition and one subtraction.
- This is a butterfly structure.
- It is a base element of a radix-2 FFT algorithm.
- FFT of length $2^{N}$ may be computed in $N$ stages, using the butterfly structure.

FFT

A radix-2 Cooley-Tukey FFT algorithm:

- The length of the signal must be a power of two: $2^{\mathrm{N}}$.
- We divide the signal into two parts, assigning samples to each part alternatively.
- We repeat this procedure until we get length 2 sequences.
- We compute the "butterflies".
- Then we compose the results into new butterflies.
- This is repeated until the whole transform is computed.


Cooley-Tukey

FFT - example for $N=8=2^{3}$


FFT - twiddle factors

- The coefficients $W$ have form:

$$
W_{N}^{k}=e^{-j 2 \pi k / N}=\cos \left(\frac{2 \pi k}{N}\right)-j \sin \left(\frac{2 \pi k}{N}\right)
$$

- They are called twiddle factors.
- $N$ is the transform length at a given stage.
- At the $i$-th stage we need $2^{i-1}$ coefficients.
- Twiddle factors are always the same for a defined transform length. Therefore, they are usually precomputed and kept in a table in memory.


## Bit reversal

- Before the transform, the samples must be set in the correct order for the first stage.
- It can be done by reversing the bit order of the indices in the binary notation (bit reversal)



## Transform length

- A classic radix-2 FFT algorithm requires that the transform length is a power of two. It is recommended to use this convention.
- The most frequently used transform lengths: 512, 1024, 2048.
- If we don't have enough samples, we can pad them with zeros to the nearest power of two. We shouldn't do this unless there are no more samples available.


## Modern FFT algorithms

FFT libraries used in practice (e.g. FFTW):

- Implementations of "butterflies" for various radices, e.g. 2, 3, 5, 7, 11, 13, 17, 19 (low prime numbers).
- The required transform length is decomposed into prime factors, e.g.: $2016=2^{5} \cdot 3^{2} \cdot 7$.
- The signal is divided into sections and FFT of radix-2/3/7 are computed, then the results are merged (a split radix algorithm).
- If one of the parts has a length which is a large prime number, a slower DFT is computed. This should be avoided.


## Comparison DFT and FFT efficiency

Taken from: Mark McKeown, FFT Implementation on the TMS320VC5505, TMS320C5505, and TMS320C5515 DSPs (SPRABB6A)

| FFT Length | Direct DFT Computation |  |  | Radix-2 FFT |
| :--- | :--- | :--- | :--- | :--- |
|  | Complex <br> Multiplications | Complex Additions | Complex <br> Multiplications | Complex Additions |
| 128 | 16,384 | 16,256 | 448 | 896 |
| 256 | 65,536 | 65,280 | 1,024 | 2,048 |
| 512 | 262,144 | 264,632 | 2,304 | 4,608 |
| 1024 | $1,048,576$ | $1,047,552$ | 5,120 | 10,240 |

For radix-2 N=1024: about five thousands of complex multiplication operations, compared with over a million multiplications for the DFT ( $200 \times$ more).

## Analysis of a continuous signal

- A Fourier transform works on blocks of samples.
- If we analyze a continuous signal, we need to divide it into blocks (windows). For each block, we compute FFT.
- This is called a short-term Fourier transform (STFT).
- Each spectrum "averages" the signal within the window over time.
- We lose short-term events inside the block.


## Analysis of a continuous signal - STFT

STFT result in a form of a spectrogram: time (horizontal) vs. frequency (vertical) vs. spectral level (color).


## Temporal resolution of STFT

- Temporal resolution depends on the window length:

$$
d t=\frac{N}{f_{S}}=\frac{1}{d f}
$$

- It is a reciprocal of frequency resolution.
- Interpretation: a minimum time difference between two events in the signal that can be distinguished in STFT.
- We can't have good temporal resolution and good frequency resolution of STFT at the same time.


## Temporal resolution of STFT

Comparison of windows of length 512 and 4096 samples.


## Overlapping

- Overlapping is achieved by moving the analysis window by less than the window length (some samples are used more than once).
- We use overlapping to:
- increase the effective temporal resolution,
- reduce the effect of applying a window function.
- Usually:
- for Hamming and von Hann window, we shift the window by $1 / 2$ of its length,
- for Blackman window, we shift it by $1 / 4$ of its length.


## FFT on digital signal processors

- Architecture and commands of digital signal processors allow for fast FFT execution.
- Some DSPs have coprocessors for FFT computation.
- The DSP maker usually provides optimized FFT procedures in Assembler, we should use them.
- Often, they are radix-2 implementations.
- We can write our own FFT implementation, bit it's not easy to obtain a faster algorithm than the one already tested.


## FFT on C5535 DSP

- The C5535 fixed point DSP (used in the course project) has a coprocessor for FFT computations (HWAFFT).
- A hardware FFT implementation for length: 8, 16, 32, 64, 128, 512, 1024.
- Uses complex signal values. If we process a real signal, we must insert zeros for the imaginary parts.
- A special procedure for bit reversal exists.
- The twiddle factors are precomputed and kept in memory.
- Two FFT stages can be computed in a single run.


## FFT on C5535 DSP

- Functions for FFT and IFFT are available from C code.
- It's easier to use functions from DSPLIB.

Documentation: SPRU422J

| Functions | Description |
| :--- | :--- |
| void cfft (DATA *x, ushort nx, type) | Radix-2 complex forward FFT - MACRO |
| void cfft32 (LDATA * $x$, ushort nx, type); | 32 -bit forward complex FFT |
| void cifft (DATA *x, ushort nx, type) | Radix-2 complex inverse FFT - MACRO |
| void cifft32 (LDATA *x, ushort nx, type); | 32 -bit inverse complex FFT |
| void cbrev (DATA *x, DATA *r, ushort n) | Complex bit-reverse function |
| void cbrev32 (LDATA *a, LDATA *r, ushort) | 32 -bit complex bit reverse |
| void rfft (DATA *x, ushort nx, type) | Radix-2 real forward FFT - MACRO |
| void rifft (DATA *x, ushort nx, type) | Radix-2 real inverse FFT - MACRO |
| void rff32 (LDATA *x, ushort nx, type) | Forward 32-bit Real FFT (in-place) |
| void rifft32 (LDATA *x, ushort nx, type) | Inverse 32-bit Real FFT (in-place) |

## Complex spectrum representation

- Spectral values are complex numbers.
- Real and imaginary parts are written separately, one after another: $\operatorname{Re}(0), \operatorname{Im}(0), \operatorname{Re}(1), \operatorname{Im}(1), \operatorname{Re}(2), \operatorname{Im}(2), \ldots$
- Each part is represented as Q15 or Q31.
- Function cfft requires a complex signal. If we have a real signal, we must insert zeros in between real values.
- For IFFT, we must write a complex spectrum as above.


## FFT of a real signal

Functions rfft and irfft use a trick:

- they treat a real signal as a complex one,
- they compute FFT of length $N / 2$,
- then they transform the result to obtain the correct one.

Therefore, we can compute FFT of maximum length 2048.
Details: Robert Matusiak, Implementing Fast Fourier Transform Algorithms of Real-Valued Sequences With the TMS320 DSP Platform (SPRA291)

WARNING: all FFT functions in DSPLIB operate in place, i.e., they overwrite the input buffer!

## FFT of a real signal

- Spectrum of a real signal is symmetric.
- From $N$ signal values, the rfft function computes $N / 2$ complex values of the spectrum, represented with $N$ numbers (real part, imaginary part).
- The first two values are real: the direct component and the Nyquist component.
- Spectrum representation: $\operatorname{Re}(0), \operatorname{Re}(N / 2), \operatorname{Re}(1), \operatorname{Im}(1), \operatorname{Re}(2), \operatorname{Im}(2), \ldots$


## Range overflow

- On fixed point DSPs, there is a risk of range overflow when FFT stages are computed.
- DSPLIB functions work in two modes.
- SCALE mode:
- results after each stage are divided by 2,
- no overflow if the input values $<1$.
- NOSCALE mode:
- no scaling,
- no overflow only if the input values < $(1 / N)$, for FFT of length $2^{N}$.

FFT of a real signal

- For a real signal, rfft function:
void rfft (DATA *x, ushort nx, type);
- Arguments:
- $x$ - pointer to a sample buffer (will be overwritten!), type DATA (= short).
- $n x$ - buffer length (the number of samples).
- type - scaling mode, we use SCALE.

```
rfft(bufor, 2048, SCALE);
```


## Project configuration for FFT

FFT functions from DSP library have the following requirements (example for $N=2048$ ).

- Memory configuration in .cmd file:

```
.fftcode > SARAM0
.data:twiddle > SARAM1, align(2048)
.input > DARAM0, align(4)
```

- Buffer declaration in C code:

```
#define N 2048
#pragma DATA_SECTION (bufor_fft, ".input")
DATA bufor_fft[N];
```

- The name ".input" is an example, any name can be used.


## A practical project - a Doppler radar

We use a DSP to analyze the signal from a microwave Doppler radar sensor.

- The emitter send an electromagnetic wave - a sine of frequency 24.125 GHz .
- The receiver gets the wave reflected from an object.
- Due to the Doppler effect, the reflected wave has different frequency than the emitted one.
- The frequency shift depends on the object speed.



## Spectrogram of a sensor signal

The difference signal - a spectrogram from a passing vehicle


## Signal analysis

The algorithm works as follows:

- the signal is analyzed in blocks of 2048 samples, with $50 \%$ overlap,
- the incoming signal samples are written into a circular buffer,
- when the buffer is full:
- the buffer is multiplied by a Hamming window,
- FFT is computed,
- power spectrum is computed,
- we look for spectral maxima (peaks),
- a vehicle speed is computed from the frequency of a spectral peak.


## Buffering of signal samples

- The incoming signal samples are written into a circular buffer of length 2048 (short numbers in Q15 format).
- The window is moved by 1024 samples. When we get 1024 new samples, then:
- we loop over the buffer, from the oldest to the latest sample,
- we multiply samples by values of the Hamming window (using _smpy function),
- we store the result in a linear buffer.


## Window function

- There is no need to compute Hamming window each time. The window values are constant for a given length.
- We compute the window values using a software.
- The values are converted to Q15.
- They are stored in a table (const short) in C code.
- Warning: the maximum value of the window is 1 . We cannot write 1 in Q15! We have to scale the window, multiplying by 32767 instead of 32768.


## Power spectrum

- We compute the complex spectrum with rfft.
- We compute the power spectrum:
- iterate over pairs (Re, Im),
- compute a square of each part (smpy),
- sum up the squared real and imaginary part,
- write the result to the buffer (we can use the same buffer).
- For amplitude spectrum, the square root of the result should be computed (sqrt_16 function from DSPLIB).


## Spectrum of a single block

Next, we analyze the spectrum, looking for the peaks.


## Peak finding

There are many methods of peak finding. An example:

- we compute a derivative of the spectrum: from each spectral value, we subtract the previous one,
- if the derivative crosses zero going down, it means the maximum is at that position,
- we also need to check the spectral amplitude to reduce the noise effect,
- we can also add other conditions, e.g. the maximum width of the peak.


## Peak finding

Power spectrum and its derivative.
A peak is found at index 104.



## Velocity calculation

All that is remaining is to compute the speed.

- Relation between frequency and speed: $v \approx 0.02234 \cdot f \quad$ (from the Doppler equation)
- Relation between the spectral index $n$ and the frequency $f$, assuming $f_{s}=48 \mathrm{kHz}: f=23.4375 \cdot n$
- So: $v \approx 0.52425 \cdot n[k m / h]$
- In Q15: $v \approx 17179 \cdot n$
- We compute: 104 * 17179 = 1786616
- In a decimal notation:

1786616 / $32768 \approx 54.52$ km/h

## Accuracy of speed measurement

- Remember that the accuracy of frequency calculation depends on the frequency resolution. For $N=2048$, the maximum error is 11.72 Hz , c.a. $0.26 \mathrm{~km} / \mathrm{h}$.
- The index of the peak may not indicate the real peak.



## Accuracy of peak finding

- We can improve the peak finding accuracy, but this method requires a division, so this algorithm is rather for floating-point processors.
- Three points determine a parabola.
- We match a parabola to the spectral peak and its two neighbors. Their values are: $a, b, c$.
- The parabola peak position is given by:

$$
m=n+\frac{1}{2} \frac{a-c}{a-2 b+c}
$$

- In our example: $m=103.8 ; v=54.42$ (was 54.52).

Źródło: https://ccrma.stanford.edu/~jos/sasp/Quadratic_Interpolation_Spectral_Peaks.html

## Accuracy of peak finding

The result of parabola matching and finding its maximum ( $\times$ ):


